

Basic principles of algorithmic graph mining Lecture 2 : Computing basic graph statistics

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## course agenda

- introduction to graph mining
- · computing basic graph statistics
- ٠
- spectral graph analysis
- additional topics and applications

algorithmic tools

# efficiency considerations

- data in the web and social-media are typically of extremely large scale (easily reach to billions)
- how to compute simple graph statistics?
- even quadratic algorithms are not feasible in practice

## hashing and sketching

- probabilistic / approximate methods
- sketching : create sketches that summarize the data and allow to estimate simple statistics with small space
- hashing: hash objects in such a way that similar objects have larger probability of mapped to the same value than non-similar objects

## estimator theorem

- consider a set of items U
- a fraction  $\rho$
- ullet estimate ho by sampling



• how many samples N are needed?

$$N \geq \frac{4}{\epsilon^2 \rho} \log \frac{2}{\delta}.$$

for an  $\epsilon\text{-approximation}$  with probability at least 1 -  $\delta$ 

• notice: it does not depend on |U| (!)

#### homework

use the Chernoff bound to derive the estimator theorem

#### computing statistics on data streams

- $X = (x_1, x_2, \dots, x_m)$  a sequence of elements
- each  $x_i$  is a member of the set  $N = \{1, ..., n\}$
- $m_i = |\{j : x_j = i\}|$  the number of occurrences of i

$$F_k = \sum_{i=1}^n m_i^k$$

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- F<sub>0</sub> is the number of distinct elements
- F<sub>1</sub> is the length of the sequence
- F<sub>2</sub> index of homogeneity, size of self-join, and other applications

## computing statistics on data streams

- How to compute the frequency moments using less than O(n log m) space?
- sketching: create a sketch that takes much less space and gives an estimation of F<sub>k</sub>

[Alon et al., 1999]

# estimating the number of distinct values $(F_0)$

[Flajolet and Martin, 1985]

- consider a bit vector of length  $O(\log n)$
- upon seen x<sub>i</sub>, set:
  - the 1st bit with probability 1/2
  - the 2nd bit with probability 1/4
  - ..
  - the i-th bit with probability 1/2i
- important: bits are set deterministically for each x<sub>i</sub>
- let R be the index of the largest bit set
- return  $Y = 2^R$

## estimating number of distinct values ( $F_0$ )

Theorem. For every c>2, the algorithm computes a number Y using O(logn) memory bits, such that the probability that the ratio between Y and  $F_0$  is not between 1/c and c is at most 2/c

# locality sensitive hashing

a family  $\mathcal H$  is called  $(R, cR, p_1, p_2)$ -sensitive if for any two objects p and q

- if  $d(p,q) \le R$ , then  $\Pr_{\mathcal{H}}[h(p) = h(q)] \ge p_1$
- if  $d(p,q) \ge cR$ , then  $\Pr_{\mathcal{H}}[h(p) = h(q)] \le p_2$

interesting case when  $p_1 > p_2$ 

## locality sensitive hashing: example

- objects in a Hamming space  $\{0,1\}^d$  binary vectors
- $\mathcal{H}: \{0,1\}^d \to \{0,1\}$  sample the *i* bit:
- $\mathcal{H} = \{h(x) = x_i \mid i = 1, ..., d\}$
- for two vectors x and y with distance r, it is

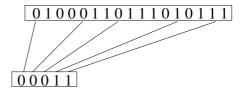
$$\Pr_{\mathcal{H}}[h(x) = h(y)] = 1 - \frac{r}{d}$$

- thus  $p_1 = 1 \frac{R}{d}$  and  $p_2 = 1 \frac{cR}{d}$
- gap between  $p_1$  and  $p_2$  too small
- probability amplification

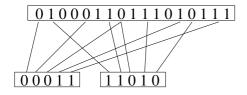
## locality sensitive hashing: Hamming distance

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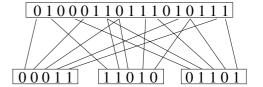
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## locality sensitive hashing: Hamming distance

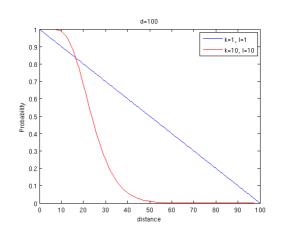


## locality sensitive hashing: Hamming distance

Probability of collision

$$\Pr[h(x) = h(y)] = 1 - (1 - (1 - \frac{r}{d})^k)^l$$

# locality sensitive hashing: Hamming distance



#### homework

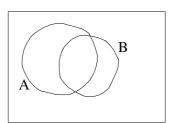
how to apply the locality sensitive hashing for vectors of integers, not just binary vectors?

vectors 
$$\mathbf{x} = \{x_1, \dots, x_d\}$$

$$L_1$$
 distance  $||\mathbf{x} - \mathbf{y}||_1 = \sum_{i=1}^{d} |x_i - y_i|$ 

#### Jaccard coefficient

- for two sets  $A, B \subseteq U$   $J(A, B) = \frac{|A \cap B|}{|A \cup B|}$
- measure of similarity of the sets



 can we design a locality sensitive hashing family for Jaccard?

## min-wise independent permutations

- $\pi: U \to U$  a random permutation of U
- $h(A) = \min\{\pi(x) \mid x \in A\}$

## min-wise independent permutations

- $\pi: U \to U$  a random permutation of U
- $h(A) = \min\{\pi(x) \mid x \in A\}$
- then

$$\Pr[h(A) = h(B)] = J(A, B) = \frac{|A \cap B|}{|A \cup B|}$$

- amplify the probability as before:
  - repeat many times,
  - concatenate into blocks
  - consider objects similar if they collide in at least one block

#### homework

show that for  $h(A) = \min\{\pi(x) \mid x \in A\}$ , with  $\pi$  a random permutation, it is

$$\Pr[h(A) = h(B)] = J(A, B) = \frac{|A \cap B|}{|A \cup B|}$$

## homework

design a locality-sensitive hashing scheme for vectors according to the cosine similarity measure

vectors 
$$\mathbf{x} = \{x_1, \dots, x_d\}$$

distance 
$$1 - \cos(\mathbf{x}, \mathbf{y}) = 1 - \frac{\mathbf{x} \cdot \mathbf{y}}{||\mathbf{x}||_2 ||\mathbf{y}||_2}$$

applications of the algorithmic tools to real scenarios

clustering coefficient and triangles

## clustering coefficient

 $C = \frac{3 \times \text{number of triangles in the network}}{\text{number of connected triples of vertices}}$ 

- how to compute it?
- how to compute the number of triangles in a graph?
- · assume that the graph is very large, stored in disk

[Buriol et al., 2006]

- count triangles when graph is seen as a data stream
- · two models:
  - edges are stored in any order
  - edges in order: all edges incident to one vertex are stored sequentially

#### counting triangles

- brute-force algorithm is checking every triple of vertices
- obtain an approximation by sampling triples



## sampling algorithm for counting triangles



- how many samples are required?
- let T be the set of all triples and
   T<sub>i</sub> the set of triples that have i edges, i = 0, 1, 2, 3
- by the estimator theorem, to get an  $\epsilon$ -approximation, with probability  $1-\delta$ , the number of samples should be

$$N \ge O(\frac{|T|}{|T_3|} \frac{1}{\epsilon^2} \log \frac{1}{\delta})$$

 $\bullet \;$  but  $|\emph{T}|$  can be very large compared to  $|\emph{T}_3|$ 

## counting triangles

- incidence model: all edges incident to each vertex appear in order in the stream
- · sample connected triples



## sampling algorithm for counting triangles

- incidence model
- consider sample space  $S = \{b\text{-}a\text{-}c \mid (a,b), (a,c) \in E\}$
- $|S| = \sum_i d_i(d_i 1)/2$
- 1: sample  $X \subseteq S$  (paths b-a-c)
- 2: estimate fraction of X for which edge (b, c) is present
- 3: scale by |S|
- gives  $(\epsilon, \delta)$  approximation

## counting triangles — incidence stream model

SAMPLETRIANGLE [Buriol et al., 2006] 1st pass count the number of paths of length 2 in the stream 2nd pass uniformly choose one path (a,b,c) 3rd pass if  $((b,c) \in E)$   $\beta=1$  else  $\beta=0$  return  $\beta$ 

## counting triangles — incidence stream model

#### properties of the sampling space

it should be possible to

- · estimate the size of the sampling space
- sample an element uniformly at random

## homework

 compute triangles in 3 passes when edges appear in arbitrary order

and space needed is  $O((1 + \frac{|T_2|}{|T_3|}) \frac{1}{\delta^2} \log \frac{1}{\delta})$ 

- 2 compute triangles in 1 pass when edges appear in arbitrary order
- 3 compute triangles in 1 pass in the incidence model

# triangle sparsifiers

[Tsourakakis et al., 2011]

- start with graph G(V, E)
- use sparsification parameter p
- pick a random subset E' of edges each edge is selected with probability p
- $T_3' = \#$  triangles on graph G'(V, E')
- return  $T_3 = T_3'/p^3$

## triangle sparsifiers

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- $T_3' = \#$  triangles on graph G'(V, E')
- return  $T_3 = T_3'/p^3$
- T<sub>3</sub> is highly concentrated around the true number of triangles

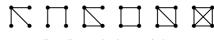
counting graph minors

## counting other minors

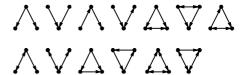
- count all minors in a very large graphs
  - connected subgraphs
  - size 3 and 4
  - directed or undirected graphs
- why?
- modeling networks, "signature" structures e.g., copying model
- anomaly detection, e.g., spam link farms [Alon, 2007, Bordino et al., 2008]

## counting minors in large graphs

• characterize a graph by the distribution of its minors



all undirected minors of size 4



all directed minors of size 3

## sampling algorithm for counting triangles

- incidence model
- consider sample space  $S = \{b \text{-}a \text{-}c \mid (a, b), (a, c) \in E\}$
- $|\mathcal{S}| = \sum_i d_i(d_i 1)/2$
- 1: sample  $X \subseteq \mathcal{S}$  (paths b-a-c)
- 2: estimate fraction of X for which edge (b, c) is present
- 3: scale by  $|\mathcal{S}|$
- $\bullet \;$  gives  $(\epsilon, \delta)$  approximation

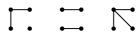
## adapting the algorithm

sampling spaces:

• 3-node directed



• 4-node undirected



are the sampling space properties satisfied?

## datasets

graph class	type	# instances
synthetic	un/directed	39
wikipedia	un/directed	7
webgraphs	un/directed	5
cellular	directed	43
citation	directed	3
food webs	directed	6
word adjacency	directed	4
author collaboration	undirected	5
autonomous systems	undirected	12
protein interaction	undirected	3
US road	undirected	12

## clustering of undirected graphs

assigned to	0	1	2	3	4	5	6
AS graph	12	0	0	0	0	0	0
collaboration	0	0	3	2	0	0	0
protein	1	0	0	1	0	0	1
road-graph	0	12	0	0	0	0	0
wikipedia	0	0	0	0	2	5	0
synthetic	11	0	0	0	0	0	28
webgraph	2	0	0	1	0	0	0

## clustering of directed graphs

accuracy compared		
to ground truth		
0.74%		
0.78%		
0.84%		
0.91%		

#### local statistics

## compute local statistics in large graphs

- our goal: compute triangle counts for all vertices
- .
- motivation
  - motifs can be used to characterize network families [Alon, 2007, Bordino et al., 2008]
  - analysis of social or biological networks
  - thematic relationships in the web
  - web spam
- applications: spam detection and content quality analysis in social media

## semi-streaming model

#### [Feigenbaum et al., 2004]

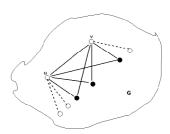
- data stream model (constant memory) too restrictive
- graph stored in secondary memory as adjacency or edge list
- no random access possible
- $O(N \log N)$  bits available in main memory
  - limited amount of information per vertex
  - x not enough to store edges in main memory
- limited (constant or  $O(\log N)$ ) number of passes
- compute counts for all vertices concurrently

## two algorithms

#### 1 external memory

- keep a counter for each vertex (main memory)
- keep a counter for each edge (secondary memory)
- 2 main memory
  - keep a counter for each vertex

## number of triangles for edges and nodes



- neighbors:  $N(u) = \{v : (u, v) \in E\}$
- degree: d(u) = |N(u)|
- edge triangles:  $T_{uv} = |N(u) \cap N(v)|$
- vertex triangles:  $T(u) = \frac{1}{2} \sum_{v \in N(u)} T_{uv}$

#### computing triangles: idea

 consider the Jaccard coefficient between two sets A and B:

$$J(A,B) = \frac{|A \cap B|}{|A \cup B|}$$

• if we knew J(N(u), N(v)) = J, then:

$$T_{uv} = |N(u) \cap N(v)| = \frac{J}{J+1}(|N(u)| + |N(v)|)$$

• and then:

$$T(u) = \frac{1}{2} \sum_{v \in N(u)} T_{uv}$$

#### computing triangles: idea

we want:

$$T_{uv} = |N(u) \cap N(v)| = \frac{J}{J+1}(|N(u)| + |N(v)|)$$

#### approximate

- m independent trials
- $Z_{uv}$ : # times that  $\min \pi(N(u)) = \min \pi(N(v))$

use the estimator:

$$\overline{T}_{uv} = \frac{Z_{uv}}{Z_{uv} + m}(|N(u)| + |N(v)|)$$

#### external-memory algorithm

- · semi-stream model
- keep vertex min-hash values (in memory)
- keep edge counters (on disk)
- use edge counters to estimate number of triangles (and local clustering coefficient)

## external-memory algorithm

```
    Z = 0
    for i: 1 ... m do {independent trials}
    for u: 1 ... | V | do {assign labels}
    l<sub>i</sub>(u) = hash<sub>i</sub>(u) {Min-wise linear permutation}
    end for
```

#### external-memory algorithm

```
1: \mathbf{Z} = \mathbf{0}

2: \mathbf{for} i: 1 ... m \mathbf{do} {independent trials}

3: \mathbf{for} u : 1 ... |V| \mathbf{do} {assign labels}

4: l_i(u) = \mathsf{hash}_i(u) {Min-wise linear permutation}

5: \mathbf{end} for

6: \mathbf{for} u : 1 ... |V| \mathbf{do} {compute fingerprints}

7: F_i(u) = \mathsf{min}_{v \in N(u)} l_i(u)

8: \mathbf{end} for{1 scan of G}
```

## external-memory algorithm

```
1: Z = 0
 2: for i: 1 ... m do {independent trials}
 3: for u : 1 ... |V| do {assign labels}
           l_i(u) = \text{hash}_i(u) {Min-wise linear permutation}
 5:
        end for
      for u : 1 ... |V| do {compute fingerprints}
 6:
 7:
          F_i(u) = \min_{v \in N(u)} I_i(u)
        end for{1 scan of G}
 8:
        \textbf{for} \ u : 1 \ldots |\textit{V}| \ \textbf{do} \ \{ update \ counters \}
 9.
           for v \in N(u) do
10:
              if (F_i(u) = F_i(v)) then {minima are equal} Z_{uv} = Z_{uv} + 1 {Z_{uv}'s stored on disk} end if
11:
12:
13:
           end for
15:
        end for
16: end for
```

#### implementation

- hash<sub>i</sub>(x) is, e.g., a linear hash function  $(a_ix + b_i \mod p)$
- for every i, the  $F_i(u)$ 's can be kept in main memory
- the Z<sub>uv</sub>'s must be stored on disk
  - for every *i*, updating Z<sub>uv</sub> requires access to disk
  - computing counters most expensive operation

## main-memory algorithm

• replace:

$$\overline{T}_{uv} = \frac{Z_{uv}}{Z_{uv} + m}(|N(u)| + |N(v)|)$$

• by the estimator for  $|N(u) \cap N(v)|$ :

$$\tilde{T}_{uv} = \frac{Z_{uv}}{\frac{2}{3}m}(N(u) + N(v))$$

• and estimator for T(u):

$$\tilde{T}(u) = \frac{1}{3m} \sum_{v \in N(u)} Z_{uv}(N(u) + N(v)) = \frac{1}{3m} Z_u$$

- $Z_u$  sums d(u) + d(v) if  $\min \pi(N(u)) = \min \pi(N(v))$
- only one counter per node

## main-memory algorithm

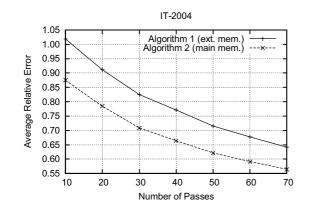
```
1: Z = 0
 2: for i: 1 ... m do {Independent trials}
       for u: 1...|V| do {Assign labels}
          I_i(u) = \text{hash}_i(u)
 4:
 5.
       end for
       for u:1\ldots |V| do
 6:
          F_i(u) = \min_{v \in V(u)} I_i(u)
       end for{1 scan of G}
 8:
       for u: 1 \dots |V| do {Update counters}
 9:
10:
          for v \in N(u) do
             if F_i(u) == F_i(v) then {Minima are equal}

Z_u = Z_u + d(u) + d(v) {Z_u's in main memory}
11:
12:
13:
          end for
14:
       end for
15:
16: end for
```

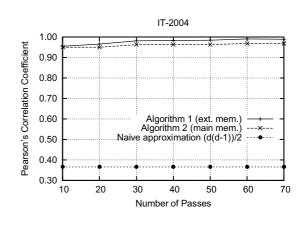
#### experimental results

			Algorithm 1	Algorithm 2
Graph	Nodes	Edges	(ext. mem.)	(main mem.)
WB-2001	118M	1.7G	10 hr 20 min	3 hr 40 min
IT-2004	41M	2.1G	8 hr 20 min	5 hr 30 min
UK-2006	77M	5.3G	20 hr 30 min	13 hr 10 min

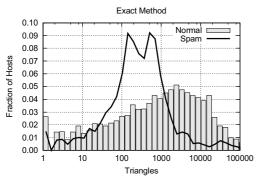
# quality of approximation



## quality of approximation

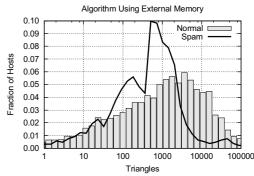


## applications: spam detection



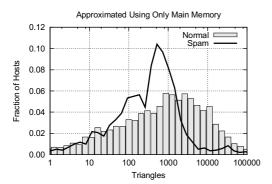
Separation of non-spam and spam hosts in the histogram of triangles

## applications: spam detection



Separation of non-spam and spam hosts in the histogram of triangles

# applications : spam detection



Separation of non-spam and spam hosts in the histogram of triangles

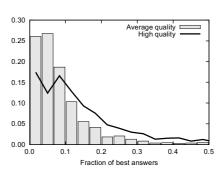
## applications: spam detection

number of triangles feature is ranked 60-th out of 221 for spam detection

## applications: content quality in yahoo! answers

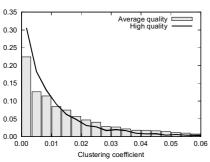
- Yahoo! answers, a question-answering portal
- consider the graph with edges (u, v) if user u has answered a question of user v
- consider "high quality" users those who have given a best answer to a random sample of questions
- predict high-quality users based on their local structure

## applications: content quality in yahoo! answers



Separation of users who have provided questions/answers of high quality with users who have provided questions/answers of normal quality in terms of fraction of best answers

## applications: content quality in yahoo! answers



Separation of users who have provided questions/answers of high quality with users who have provided questions/answers of normal

graph distance distributions

## small-world phenomena

small worlds: graphs with short paths



- Stanley Milgram (1933-1984)
   "The man who shocked the world"
- obedience to authority (1963)
- small-world experiment (1967)

#### Milgram's experiment

- 300 people (starting population) are asked to dispatch a parcel to a single individual (target)
- the target was a Boston stockbroker
- the starting population is selected as follows:
  - 100 were random Boston inhabitants (group A)
  - 100 were random Nebraska strockbrokers (group B)
  - 100 were random Nebraska inhabitants (group C)

## Milgram's experiment

- · rules of the game :
- parcels could be directly sent only to someone the sender knows personally
- 453 intermediaries happened to be involved in the experiments (besides the starting population and the target)

## Milgram's experiment

questions Milgram wanted to answer:

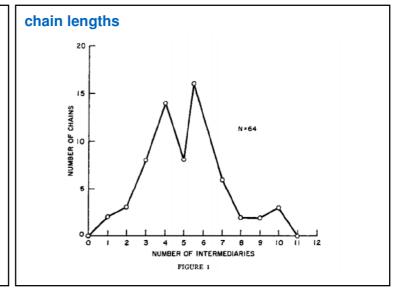
- 1. how many parcels will reach the target?
- 2. what is the distribution of the number of hops required to reach the target?
- 3. is this distribution different for the three starting subpopulations?

## Milgram's experiment

answers to the questions

- 1. how many parcels will reach the target?
- what is the distribution of the number of hops required to reach the target? average was 5.2
- 3. is this distribution different for the three starting subpopulations?

YES: average for groups A/B/C was 4.6/5.4/5.7



#### measuring what?

but what did Milgram's experiment reveal, after all?

- 1. the the world is small
- 2. that people are able to exploit this smallness

#### graph distance distribution

- obtain information about a large graph, i.e., social network
- · macroscopic level
- distance distribution
  - mean distance
  - median distance
  - diameter
  - effective diameter
  - ..

## graph distance distribution

- given a graph, d(x, y) is the length of the shortest path from x to y  $\infty$  if one cannot go from x to y
- for undirected graphs, d(x, y) = d(y, x)
- for every t, count the number of pairs (x, y) such that d(x, y) = t
- the fraction of pairs at distance t is a distribution

## exact computation

how can one compute the distance distribution?

- weighted graphs: Dijkstra (single-source:  $O(m \log n)$ ),
- Floyd-Warshall (all-pairs:  $O(n^3)$ )
- in the unweighted case:
  - $\bullet\,$  a single BFS solves the single-source version of the problem:  $\mathcal{O}(m)$
  - if we repeat it from every source: O(nm)

## sampling pairs

- sample at random pairs of nodes (x, y)
- compute d(x, y) with a BFS from x
- (possibly: reject the pair if d(x, y)

## sampling pairs

- for every t, the fraction of sampled pairs that were found at distance t are an estimator of the value of the probability mass function
- takes a BFS for every pair O(m)

## sampling sources

- sample at random a source t
- ullet compute a full BFS from t

# sampling sources

- it is an unbiased estimator only for undirected and connected graphs
- uses anyway BFS...
  - ...not cache friendly
  - ... not compression friendly

# idea: diffusion

[Palmer et al., 2002]

- let B<sub>t</sub>(x) be the ball of radius t around x (the set of nodes at distance ≤ t from x)
- clearly  $B_0(x) = \{x\}$
- moreover  $B_{t+1}(x) = \bigcup_{(x,y)} B_t(y) \bigcup \{x\}$
- so computing  $B_{t+1}$  from  $B_t$  just takes a single (sequential) scan of the graph

## easy but costly

- every set requires O(n) bits, hence  $O(n^2)$  bits overall
- · easy but costly
- too many!
- what about using approximated sets?
- we need probabilistic counters, with just two primitives:
   add and size
- very small!

## estimating the number of distinct values $(F_0)$

- [Flajolet and Martin, 1985]
- consider a bit vector of length  $O(\log n)$
- upon seen x<sub>i</sub>, set:
  - the 1st bit with probability 1/2
  - the 2nd bit with probability 1/4
  - ...
  - the i-th bit with probability 1/2i
- important: bits are set deterministically for each x<sub>i</sub>
- let R be the index of the largest bit set
- return  $Y = 2^R$

#### **ANF**

- probabilistic counter for approximating the number of distinct values [Flajolet and Martin, 1985]
- ANF algorithm [Palmer et al., 2002] uses the original probabilist counters
- HyperANF algorithm [Boldi et al., 2011] uses HyperLogLog counters [Flajolet et al., 2007]

## **HyperANF**

- HyperLogLog counter [Flajolet et al., 2007]
- with 40 bits you can count up to 4 billion with a standard deviation of 6%
- remember: one set per node

# implementation tricks

[Boldi et al., 2011]

- use broad-word programming
- systolic computation for on-demand updates of counters
- exploit micro-parallelization of multicore architectures

#### performance

- HADI, a Hadoop-conscious implementation of ANF [Kang et al., 2011]
- takes 30 minutes on a 200K-node graph (on one of the 50 world largest supercomputers)
- HyperANF does the same in 2.25min on a workstation (20 min on a laptop).

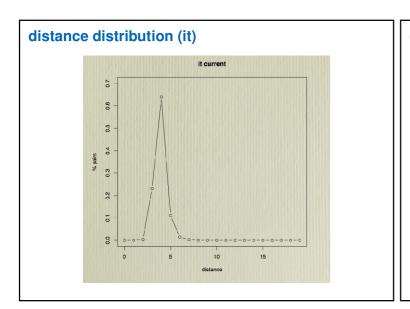
#### experiments on facebook

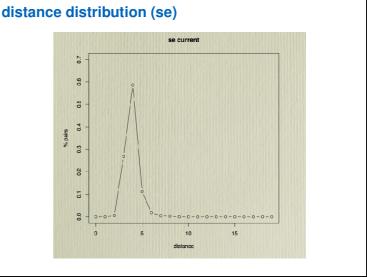
[Backstrom et al., 2011]

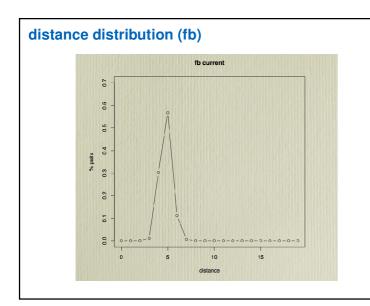
considered only active users

- it : only italian users
- se : only swedish users
- it + se : only italian and swedish users
- us : only US users
- the whole facebook (750m nodes)

based on users current geo-IP location









fb 2012 : 92% pairs are reachable!

## effective diameter

	2008	2012
it	9.0	5.2
se	5.9	5.3
it+se	6.8	5.8
us	6.5	5.8
fb	7.0	6.2

## actual diameter

average distance

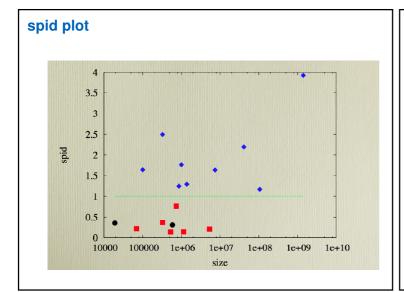
	2008	2012
it	> 29	= 25
se	> 16	= 25
it+se	> 21	= 27
us	> 17	= 30
fb	> 17	> 58



## another application: spid

[Boldi et al., 2011]

- spid : shortest-paths index of dispersion
- the ratio between variance and average in the distance distribution
- spid < 1 : the distribution is subdispersed
- spid > 1 : is superdispersed
- web graphs and social networks have different spid!



## the spid conjecture

- [Boldi et al., 2011] conjecture that spid is able to tell social networks from web graphs
- average distance alone would not changeable and depends on the scale
- spid, instead, seems to have a clear cutpoint at 1
- what is facebook spid?

## the spid conjecture

- [Boldi et al., 2011] conjecture that spid is able to tell social networks from web graphs
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0.093

indexing distances in large graphs

## shortest-path distances in large graphs

- input: consider a graph G = (V, E)
- and nodes s and t in V
- goal: compute the shortest-path distance d(s,t) from s to t
- do it very fast

## well-studied problem

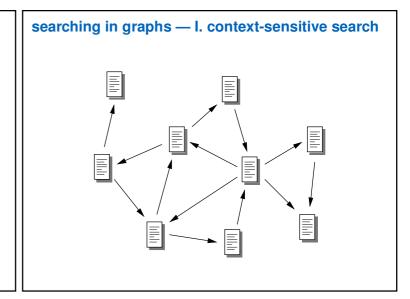
#### different strategies

- lazy
  - compute shortest path at query time
  - Dijkstra, BFS
  - no precomputation
  - BFS takes O(m)
  - too expensive for large graphs

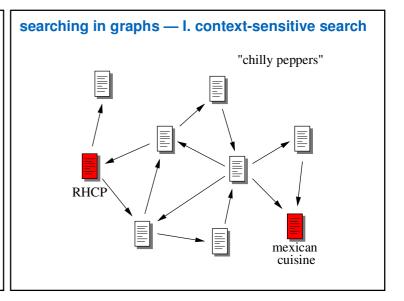
#### eager

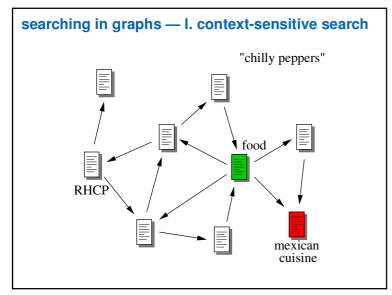
- precompute all-pairs shortest paths
- Floyd-Warshall, matrix multiplication
- $O(n^3)$  precomputation,  $O(n^2)$  storage
- too large to store

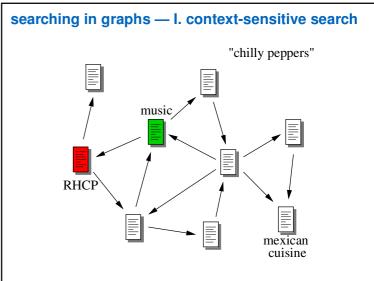
## applications of shortest-path queries



# searching in graphs — I. context-sensitive search "chilly peppers"

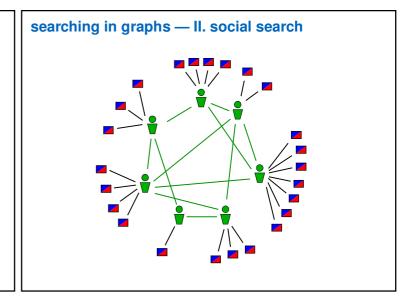


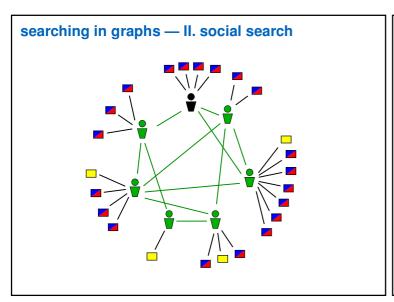


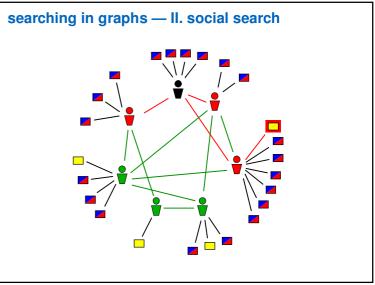


# searching in graphs — I. context-sensitive search

- customize search results to the user's current page or recent history of pages have visited
- increasing relevance of answers
- disambiguation
- suggesting links to wikipedia editors







## searching in graphs — II. social search

- consider more information than just contacts
  - preferences
  - geographical information
  - comments
  - favorites
  - tags
  - · etc.

#### machine-learning approach

• learn a ranking function that combines a large number of features

#### content-based features:

- TF/IDF, BM25, etc., as in traditional IR and web search
- content similarity between the querying node and a target

#### link-based features:

- PageRank
- shortest-path distance from the querying node to a target
- spectral distance from the querying node to a target node
- · graph-based similarity measures

#### well-studied problem

#### different strategies

- lazy
  - compute shortest path at query time
  - Dijkstra, BFS
  - no precomputation
  - BFS takes O(m)
  - too expensive for large graphs
- eager
  - precompute all-pairs shortest paths
  - Floyd-Warshall, matrix multiplication
  - $O(n^3)$  precomputation,  $O(n^2)$  storage
  - too large to store

# anything in between?

• is there a smooth tradeoff between

$$\langle O(1), O(m) \rangle$$
 and  $\langle O(n^2), O(1) \rangle$ 

## distance oracles

## [Thorup and Zwick, 2005]

- given a graph G = (V, E)
- an  $(\alpha, \beta)$ -approximate distance oracle is a data structure S that
- for a query pair of nodes (u, v), S returns  $d_S(u, v)$  s.t.

$$d(u, v) \le d_S(u, v) \le \alpha d(u, v) + \beta$$

- ullet  $\alpha$  called stretch or distortion
- consider the preprocessing time, the required space, and the query time

#### distance oracles

#### [Thorup and Zwick, 2005]

- given k, construct an oracle with storage  $O(kn^{1+1/k})$ , query time O(k), stretch 2k-1
- k = 1 $\Rightarrow$  APSP
- $k = \log n$  $\Rightarrow$  storage  $O(n \log n)$ , query time  $O(\log n)$ , stretch  $O(\log n)$

## distance oracles — preprocessing

[Das Sarma et al., 2010]

- 1  $r = |\log |V||$
- 2 sample r + 1 sets of sizes  $1, 2, 2^2, 2^3, \dots, 2^r$
- 3 call the sampled sets  $S_0, S_1, \ldots, S_r$
- 4 for each node u and each set  $S_i$  compute  $(w_i, \delta_i)$ , where  $\delta_i = d(u, w_i) = \min_{v \in S_i} \{d(u, v)\}$
- **5** SKETCH[u] = { $(w_0, \delta_0), \dots, (w_r, \delta_r)$ }
- 6 repeat k times

#### distance oracles — query processing

[Das Sarma et al., 2010]

given query (u, v)

- $\bigcirc$  obtain SKETCH[u] and SKETCH[v]
- w in SKETCH[u] and SKETCH[v]
- 3 for each common node w, compute d(u, w) and d(w, v)
- 4 return the minimum of d(u, w) + d(w, v), taken over all common node w's
- **5** if no common w is present, then return  $\infty$

#### landmark-based approach

- precompute:
- then

$$|d(s,l)-d(t,l)| \leq d(s,t) \leq d(s,l) + d(l,t)$$

• precompute: distances to d landmarks,  $l_1, \ldots, l_d$ 

$$\max_i |d(s,l_i) - d(t,l_i)| \le d(s,t) \le \min_i (d(s,l_i) + d(l_i,t))$$

- obtain a range estimate in time O(d) (i.e., constant)

#### landmark-based approach

- motivated by indexing general metric spaces
- used for estimating latency in the internet [Ng and Zhang, 2008]
- typically randomly chosen landmarks

## theoretical results

[Kleinberg et al., 2004]

- random landmarks can provide distance estimates with distortion  $(1+\delta)$  for a fraction of at least  $(1-\epsilon)$  of pairs
- number of landmarks required depends on  $\epsilon$ ,  $\delta$ , and the doubling dimension k of the metric space

## approximation guarantee in practice

what does a logarithmic approximation guarantee mean in a small-world graph?

# the landmark selection problem

how to choose good landmarks in practice?

#### good landmarks

if 
$$s = 1$$
 then  $d(s, t) = d(s, l) + d(l, t)$ 

if 
$$1 \bullet \bullet \bullet$$
 then  $|d(s, l) - d(t, l)| = d(s, t)$ 

#### good (upper-bound) landmarks

- a landmark / covers a pair (s,t) if / is on a shortest path from s to t
- problem definition:  $L \subseteq V$  of k landmarks that cover as many pairs  $(s,t) \in V \times V$  as possible
- NP-hard
- for k = 1: the node with the highest centrality betweenness
- for k > 1: apply a "natural" set-cover approach (but O(n³))

#### landmark selection heuristics

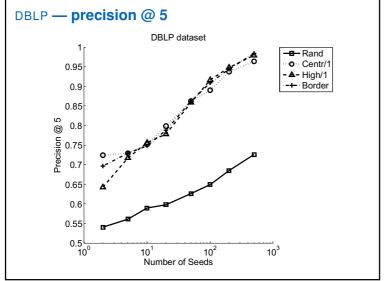
- · high-degree nodes
- high-centrality nodes
- "constrained" versions
  - once a node is selected none of its neighbors is selected
- "clustered" versions
  - cluster the graph and select one landmark per cluster
  - select landmarks on the "borders" between clusters

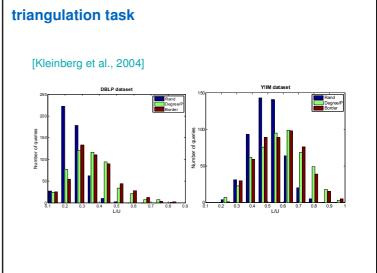
## datasets

# nodes # edges median effective clustering distance diameter coefficient

DBLP 226 K 716 K 9 13 0.47

#### flickr-implicit — distance error Flickr Implicit dataset 0.6 ---- Rand • O · Centr/1 0.55 **- ▲-** High/1 0.5 -+ Border 0.45 0.4 Ē 0.35 0.3 0.25 0.2 0.15 0.1 10<sup>0</sup> 10<sup>3</sup> 10<sup>2</sup> Number of Seeds





#### comparing with exact algorithm

[Goldberg and Harrelson, 2005]

landmarks (10%)	FIE	FlI	Wiki	DBLP	Y!IM
Method	CENT	CENT	CENT/P	Bord/P	Bord/P
Landmarks used	20	100	500	50	50
Nodes visited	1	1	1	1	1
Operations	20	100	500	50	50
CPU ticks	2	10	50	5	5
ALT (exact)	FIE	FlI	Wiki	DBLP	Y!IM
Method	Ikeda	lkeda	Ikeda	Ikeda	Ikeda
Landmarks used	8	4	4	8	4
Nodes visited	7245	10337	19616	2458	2162
Operations	56502	41349	78647	19666	8648
CPU ticks	7062	10519	25868	1536	1856

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